The Augmented Factorization Bound for Maximum-Entropy Sampling

Yongchun Li

Department of Industrial and Systems Engineering University of Tennessee, Knoxville

Mixed Integer Programming Workshop 2025

June 3, 2025

Maximum Entropy Sampling Problem (MESP)



Figure: A 54-node network to measure the temperature (Bodik et al., 2004))

Sensor placement problem

- $[n] = \{1, 2, \dots, n\}$: *n* available locations
- $x \in \mathbb{R}^n$: *n* random variables, e.g., temperature at *n* locations
- Goal: Choose a subset S ⊆ [n], with |S| = s, to place sensors so that observing x_S maximizes the "information" about x

Maximum Entropy Sampling Problem (MESP)

- Entropy measures information (Shannon, 1948)
- Suppose that x follows Gaussian distribution with covariance matrix C. Then, the entropy obtained from observing x_S is

$$h(x_{S}) = \frac{1}{2}\log\det(C_{S,S}) + \frac{1}{2}(1 + \log(2\pi))s$$

where

- $C_{S,S}$: A principal submatrix of C indexed by S
- log det: The natural logarithm of the determinant function

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(MESP)
$$v^* := \max_{S} \{ \log \det (C_{S,S}) : S \subseteq [n], |S| = s \}$$

• MESP is NP-hard (Ko et al., 1995)

Existing upper bounds of MESP

- Spectral bounds: Bound the determinant based on the properties of eigenvalues
 - (Ko et al., 1995, Anstreicher and Lee, 2004, Burer and Lee, 2007, ...)
- Convex relaxation bounds
 - ▶ NLP bound (Anstreicher et al., 1999)
 - ▶ BQP bound (Anstreicher, 2018)
 - ► Linx bound (Anstreicher, 2020)
 - ► Factorization bound (Nikolov 2015, Li and Xie, 2024, Chen et al. 2023).

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This paper improves upon the factorization bound

Factorization bound of MESP (Nikolov, 2015)

Recall

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$$v^* := \max_{S} \{ \log \det (C_{S,S}) : S \subseteq [n], |S| = s \}$$

• Assume that the covariance matrix C is positive definite

• Factorize C: $C = A^{\top}A$

Lemma (Nikolov, 2015): Reformulation of MESP

$$(\mathsf{MESP}) \quad v^* := \max_{z \in \{0,1\}^n} \left\{ \log \det^s \left(A \mathsf{Diag}(z) A^\top \right) : \sum_{i \in [n]} z_i = s \right\},$$

where function $\frac{s}{\det}$ is the product of s largest eigenvalues of a matrix.

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where function det is the product of *s* largest eigenvalues of a matrix.

- However, this is not a convex program
- Its Lagrangian dual yields the factorization bound

The augmented factorization bound of MESP

- First, subtract a scaled identity matrix tI_n from C, where $0 \le t \le \lambda_{\min}(C)$
- Second, factorize the positive semidefinite matrix $C tI_n$
- Finally, derive the Lagrangian dual of MESP

Theorem

As t increases, the Lagrangian dual bound becomes tighter.

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Theorem

As t increases, the Lagrangian dual bound becomes tighter.

- The factorization bound: t = 0
- The augmented factorization bound: $t = \lambda_{\min}(C)$
- The improvement depends on the condition number of C

Three benchmark datasets: n = 63, 90, 124

- Fact: The factorization bound (Nikolov, 2015)
- Linx: The linx bound (Anstreicher 2020)
- Mix-LF: Combine Fact and Linx (Chen et al., 2023)
- Aug-Fact: Our augmented factorization bound
- Integrality gap := Upper bound Optimal value



Figure: Integrality gap of n = 63, where the condition number of C is 48.42

Three benchmark datasets: n = 63, 90, 124



Figure: Integrality gap of n = 90, where the condition number of C is 200.45

Three benchmark datasets: n = 63, 90, 124



Figure: Integrality gap of n = 124, where the condition number of C is 78340.48

Thank you!

https://arxiv.org/pdf/2410.10078. Accepted at IPCO 2025